

# Random Assignment with Optional Participation

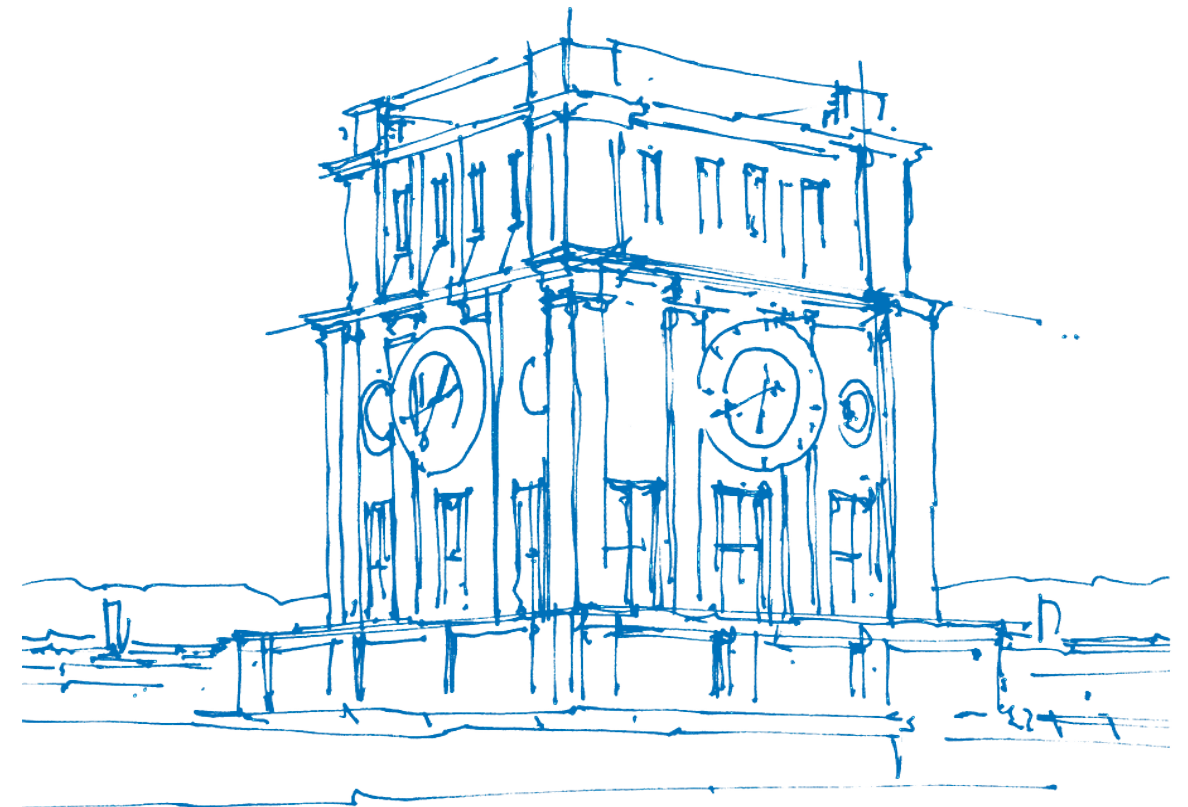
*Joint work with Florian Brandl and Felix Brandt*

Johannes Hofbauer

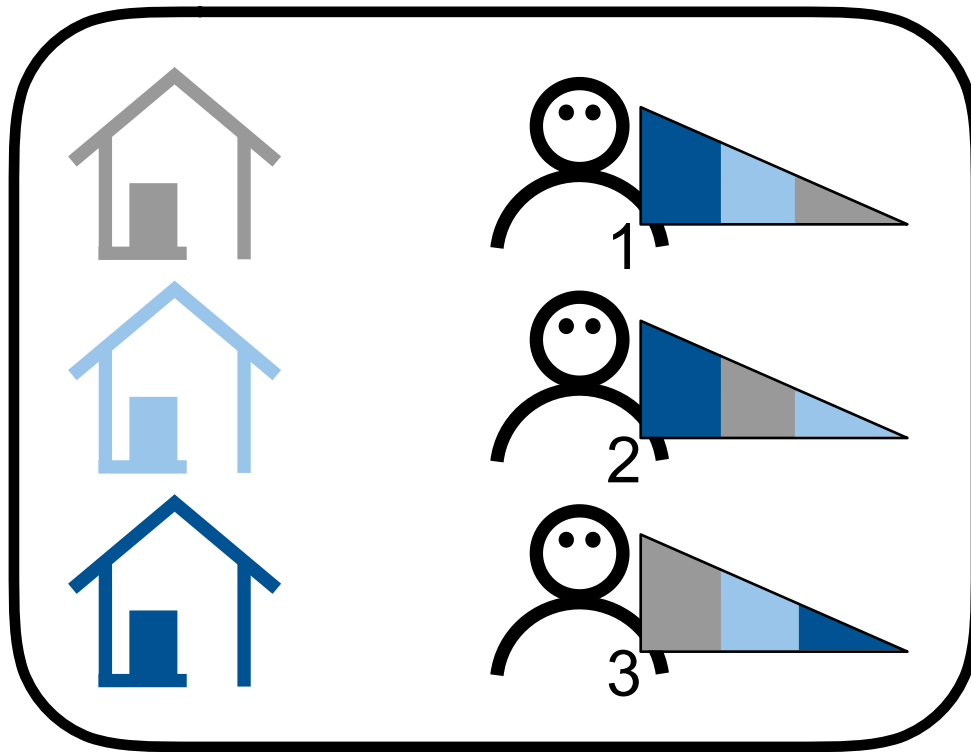
Technische Universität München

16<sup>th</sup> AAMAS Conference

Sao Paulo, May 10, 2017



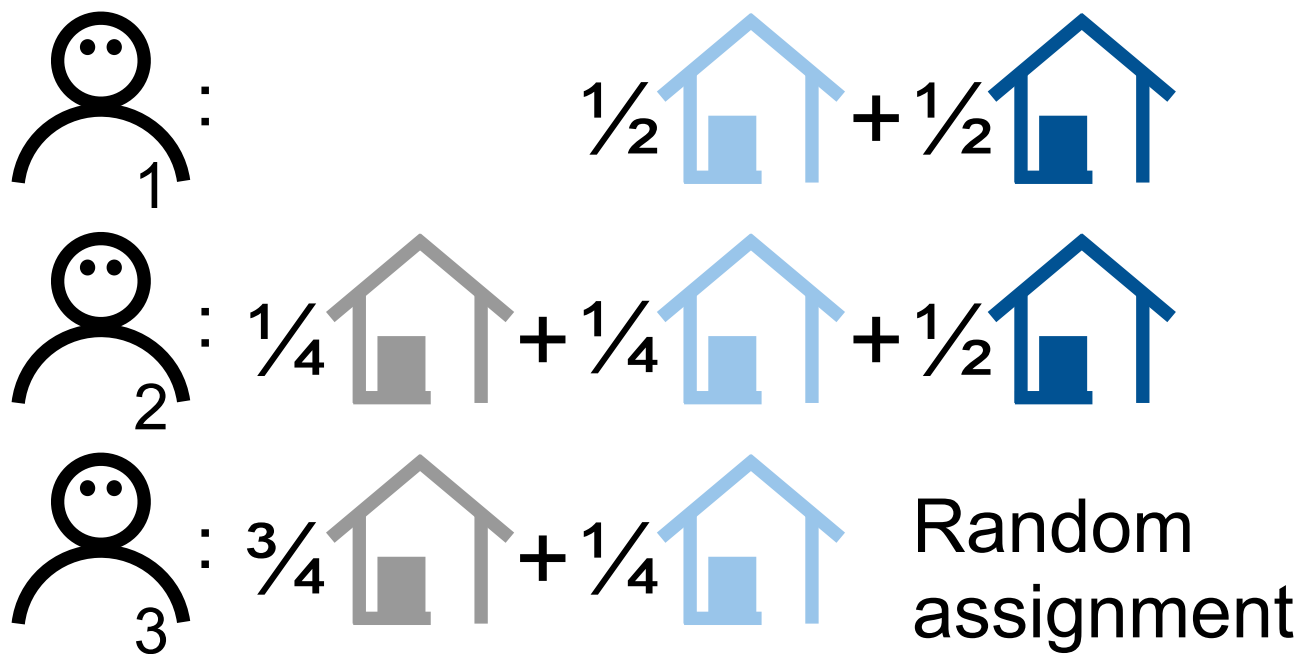
*TUM Uhrenturm*



Assignment problem

Random assignment rule

Assignment rule



Deterministic assignment



- A company wants to allocate offices to workers
  - ▶ everybody has to receive something
- Determining / submitting one's preferences is associated with effort / cost



• Allocation of if he participates:  $\frac{1}{2}$  +  $\frac{1}{6}$  +  $\frac{1}{3}$

• Allocation of if he abstains:

• According to stochastic dominance (SD)  $\frac{1}{2}$  +  $\frac{1}{6}$  +  $\frac{1}{3}$  >

- Is there always an incentive to participate?
  - (i) How to model participation?
  - (ii) How to define incentives?

# Modeling participation

Two ways to define abstention:

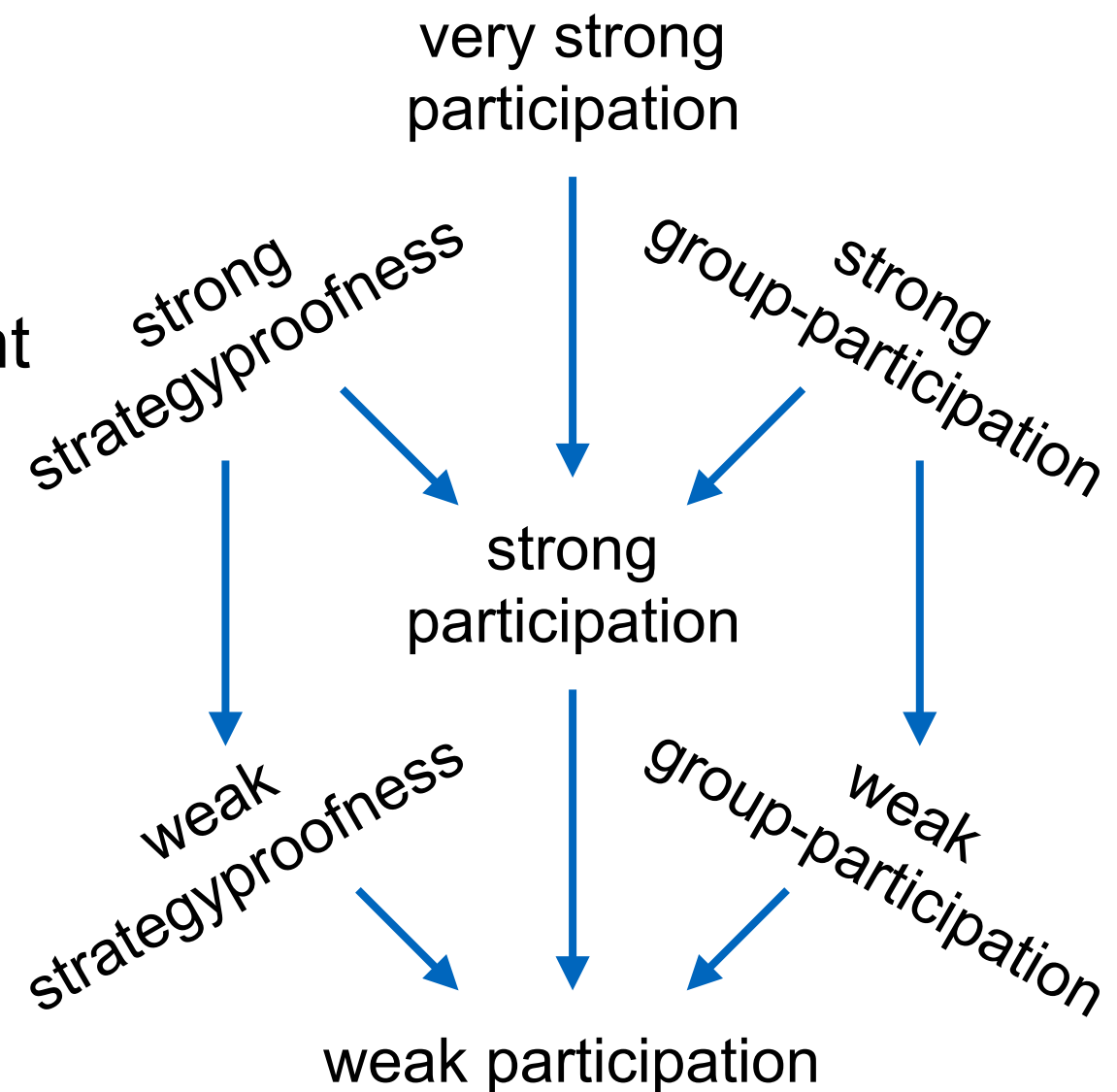
- indifference** absent agents treated as if they were completely indifferent
- two rounds**
  - (1) participating agents get probability share 1 according to preferences
  - (2) remaining probability shares distributed uniformly to absent agents

→ both interpretations equivalent for the random assignment rules considered

# Defining incentives

Three notions of SD-participation [Brandl et al., 2015]:

- weak participation**     participating cannot yield a worse assignment
- strong participation**     participating always yields a (weakly) better assignment
- very strong participation**     participating always yields a strictly better assignment



# Random serial dictatorship (RSD)

- **Assignment rule**

- ▶ select a sequence of agents uniformly at random
- ▶ in this order, every agent picks his most preferred remaining house

- **Participation**

- ▶ RSD satisfies very strong participation
- ▶ RSD satisfies strong group-participation



$$\text{RSD} = \begin{matrix} \text{Agent 1} \\ \text{Agent 2} \\ \text{Agent 3} \end{matrix} \begin{bmatrix} \frac{1}{2} & \frac{1}{6} & \frac{1}{3} \\ \frac{1}{2} & \cdot & \frac{1}{2} \\ \cdot & \frac{5}{6} & \frac{1}{6} \end{bmatrix}$$

# (Extended) Probabilistic Serial (PS)

## • Assignment rule

- ▶ each agent reserves probability of his first indifference class of houses at uniform speed
- ▶ when a set of houses is completely reserved, agents continue with their most preferred still available indifference class



## • Participation

- ▶ PS satisfies very strong participation
- ▶ PS satisfies strong group-participation

$$PS = \begin{matrix} & \begin{matrix} \text{House 1} & \text{House 2} & \text{House 3} \end{matrix} \\ \begin{matrix} \text{Agent 1} \\ \text{Agent 2} \\ \text{Agent 3} \end{matrix} & \begin{bmatrix} 1/2 & 1/4 & 1/4 \\ 1/2 & \cdot & 1/2 \\ \cdot & 3/4 & 1/4 \end{bmatrix} \end{matrix}$$

# (Naive) Boston Mechanism (BM)

## • Assignment rule

- ▶ in the  $i^{th}$  round, every remaining house is assigned to an agent ranking it at  $i^{th}$  place uniformly at random
- ▶ all assigned agents and houses leave the procedure after each round



## • Participation

- ▶ BM satisfies very strong participation
- ▶ BM does not satisfy strong group-participation
- ▶ BM satisfies weak group-participation

$$\text{BM} = \begin{matrix} \text{Agent 1} \\ \text{Agent 2} \\ \text{Agent 3} \end{matrix} \begin{bmatrix} \frac{1}{2} & \cdot & \frac{1}{2} \\ \frac{1}{2} & \cdot & \frac{1}{2} \\ \cdot & 1 & \cdot \end{bmatrix}$$



# Popular random assignment rules (PRA)

## • Class of assignment rules

- ▶ random assignments, such that there does not exist another random assignment which is majority preferred
- ▶ correspond to (probabilistic) weak Condorcet-winners in the majority graph



## • Participation

- ▶ PRA do not satisfy very strong participation
- ▶ PRA do not satisfy strong group-participation
- ▶ PRA satisfy weak group-participation
- ▶ **Open problem:**  
Do PRA satisfy strong participation?

$$\text{PRA} = \begin{matrix} \begin{matrix} \text{House A} & \text{House B} & \text{House C} \end{matrix} \\ \begin{matrix} \text{Agent 1} \\ \text{Agent 2} \\ \text{Agent 3} \end{matrix} \end{matrix} \begin{bmatrix} \lambda & \cdot & 1-\lambda \\ 1-\lambda & \cdot & \lambda \\ \cdot & 1 & \cdot \end{bmatrix}$$

# Overview & conclusion

	Very strong participation	Strong group-participation	Weak group-participation
Random Serial Dictatorship	✓	✓	✓
Probabilistic Serial	✓	✓	✓
Boston Mechanism	✓	✗	✓
Popular random assignment rules	✗	✗	✓

- Results largely positive; participating (basically) always incentivized